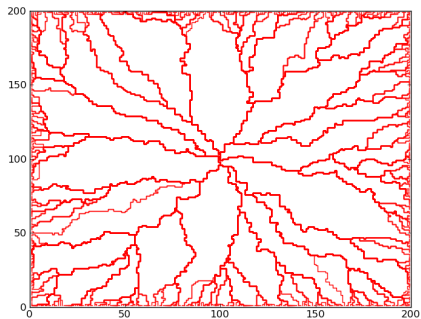


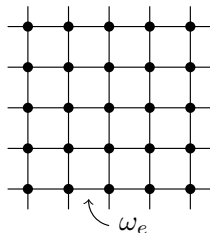
Geodesics in first-passage percolation

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Based on joint work with Christopher Hoffman (and Jack Hanson).

A model for spatial growth



In **first-passage percolation** the edges of \mathbb{Z}^2 are assigned i.i.d. weights $\omega_e \geq 0$ from a continuous distribution with finite mean. A random metric:

$$T(x, y) := \inf \left\{ \sum_{e \in \pi} \omega_e : \pi \text{ is a path from } x \text{ to } y \right\}.$$

Goal: Understand the asymptotics of distances, balls and geodesics.



Subadditive ergodic theory

Key property: $T(x, y) \leq T(x, z) + T(z, y)$ for all $x, y, z \in \mathbb{Z}^2$.

Hammersley-Welsh (1965): $\exists \mu(z) := \lim_{n \rightarrow \infty} \frac{1}{n} T(0, nz)$ in probability.

Kingman (1968): The limit exists almost surely.

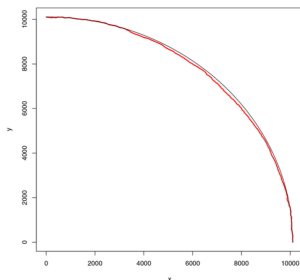
The shape theorem

Richardson (1973), Cox-Durrett (1981): There exists a compact and convex set $\text{Ball} \subset \mathbb{R}^2$ such that, almost surely, for all large t

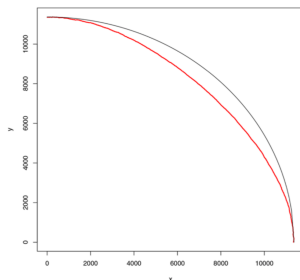
$$(1 - \varepsilon)\text{Ball} \subset \frac{1}{t} \{z \in \mathbb{Z}^2 : T(0, z) \leq t\} \subset (1 + \varepsilon)\text{Ball}.$$

First Passage Percolation on \mathbb{Z}^2 : A Simulation Study

Alm-Deijfen (2015)



(a) $\text{Exp}(1)$



(b) $0.5 + \text{Exp}(1)$

KPZ universality

Kardar-Parisi-Zhang (1986): Predictions due to physicists suggest that

$T(0, ne_1)$ fluctuates around its mean by order n^χ

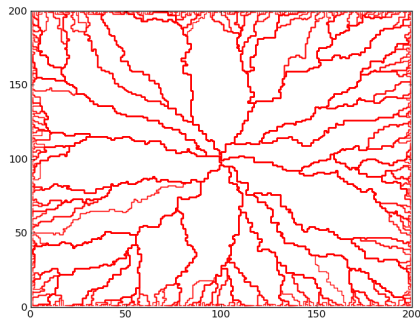
$\text{Geo}(0, ne_1)$ fluctuates vertically by order n^ξ

where the exponents should equal $\chi = 1/3$ and $\xi = 2/3$, so $\chi = 2\xi - 1$.



Geodesics in first-passage percolation

The **geodesic** between x and y is the path whose weight-sum equals $T(x, y)$. Consider the geodesics from the origin to sites at distance n . We want to describe the geometry of this object when n is large.



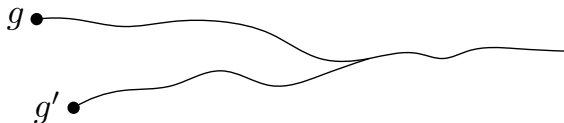
(Simulation for exponential weights, from *mathoverflow*.)

Geodesics in first-passage percolation

An infinite path is an **infinite geodesic** if every finite segment is a geodesic. A geodesic $g = (v_1, v_2, \dots)$ has **asymptotic direction** θ if

$$\lim_{k \rightarrow \infty} \frac{v_k}{|v_k|} = \theta.$$

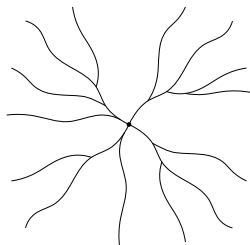
Two infinite geodesics g and g' **coalesce** if $g \Delta g'$ is finite.



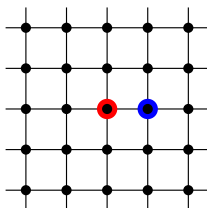
Newman's conjectures

Conditional work of **Newman (1995)** led to the following conjectures:

- (I) With probability one, every infinite geodesic has a direction.
- (II) For every θ there is an a.s. *unique* geodesic in \mathcal{T}_0 with direction θ .
- (III) For every θ any two geodesics with direction θ *coalesce* a.s.



A model for competing growth



In the **two-type Richardson model** we initially color $(0,0)$ **red** and $(1,0)$ **blue**. As time evolves, uncolored sites of \mathbb{Z}^2 turn

red at rate $1 \cdot \#\{\text{red neighbors}\}$

blue at rate $\lambda \cdot \#\{\text{blue neighbors}\}$

A colored site keeps its color forever.

Central question: For which values of $\lambda \geq 1$ is it possible for both **red** and **blue** to conquer infinitely many sites?

Coexistence and existence of multiple geodesics

Let \mathcal{T}_0 denote the set of infinite geodesics starting at the origin.

Häggström-Pemantle (1998):

- (i) When $\lambda = 1$, coexistence occurs with positive probability.
- (ii) For exponential weights, $\mathbb{P}(|\mathcal{T}_0| \geq 2) > 0.064$.

Hoffman (2008): $\mathbb{P}(|\mathcal{T}_0| \geq 4) > 0$.

Damron-Hanson (2014): $\mathbb{P}(|\mathcal{T}_0| \geq 4) = 1$.

Busemann functions

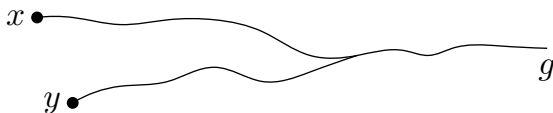
For a geodesic $g = (v_1, v_2, \dots)$ we define its **Busemann function** as

$$B_g(x, y) := \lim_{k \rightarrow \infty} [T(x, v_k) - T(y, v_k)].$$

The limit exists for all g and satisfies

$$B_g(0, y) = T(0, y) \text{ for all } y \in g.$$

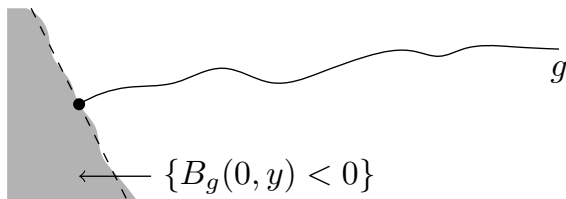
$B_g(0, y) < 0$ iff y further 'from infinity' than the origin along g .



Busemann functions

A linear functional $\rho : \mathbb{R}^2 \rightarrow \mathbb{R}$ is called **supporting** if the line $\{x \in \mathbb{R}^2 : \rho(x) = 1\}$ is a supporting line to Ball . Given a supporting functional ρ and a geodesic g we say that the Busemann function of g is **asymptotically linear** to ρ if

$$\limsup_{|y| \rightarrow \infty} \frac{1}{|y|} |B_g(0, y) - \rho(y)| = 0.$$



Asymptotic directions

From ρ we can read out the **direction** of $g = (v_1, v_2, \dots)$.

$$\rho(v_k/|v_k|) \approx \frac{1}{|v_k|} B_g(0, v_k) = \frac{1}{|v_k|} T(0, v_k) \approx \mu(v_k/|v_k|).$$

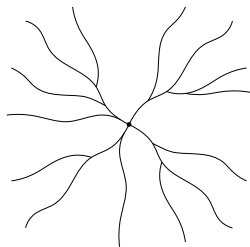
So any limit point x of $(\frac{v_k}{|v_k|})_{k \geq 1}$ must satisfy $\rho(x) = \mu(x)$.

Damron-Hanson (2014): For every **tangent** functional ρ there exists a geodesic in \mathcal{T}_0 with Busemann function linear to ρ .

Newman's conjectures

Conditional work of **Newman (1995)** led to the following conjectures:

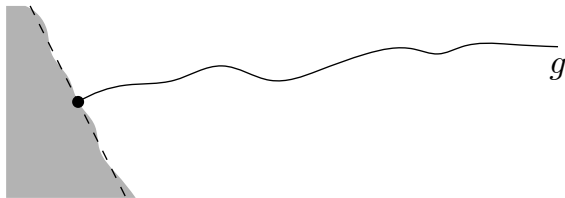
- (I) With probability one, *every* infinite geodesic has a direction.
- (II) For *every* θ there is an a.s. *unique* geodesic in \mathcal{T}_0 with direction θ .
- (III) For every θ any two geodesics with direction θ *coalesce* a.s.



Versions of Newman's conjectures

(I) With probability one, every infinite geodesic has a direction.

Theorem I: (A.-Hoffman) With probability one, every infinite geodesic has a linear Busemann function.



Versions of Newman's conjectures

(II) For every direction θ there is an a.s. *unique* geodesic with direction θ .

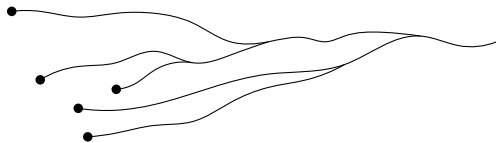
Theorem II: (A.-Hoffman) There is a deterministic set \mathcal{C} such that, a.s., the set of functionals ρ for which there exists a geodesic in \mathcal{T}_0 with Busemann function linear to ρ equals \mathcal{C} . Moreover, for every $\rho \in \mathcal{C}$

$$\mathbb{P}(\exists \text{ two geodesics in } \mathcal{T}_0 \text{ with Busemann function linear to } \rho) = 0.$$

Versions of Newman's conjectures

(III) For every direction θ any two geodesics with direction θ *coalesce* a.s.

Theorem III: (A.-Hoffman) For every $\rho \in \mathcal{C}$, any two geodesics with Busemann function linear to ρ coalesce a.s.



Versions of Newman's conjectures

Theorem I: (A.-Hoffman) With probability one, every infinite geodesic has a linear Busemann function.

Theorem II: (A.-Hoffman) There is a deterministic set \mathcal{C} such that, a.s., the set of functionals ρ for which there exists a geodesic in \mathcal{T}_0 with Busemann function linear to ρ equals \mathcal{C} . Moreover, for every $\rho \in \mathcal{C}$

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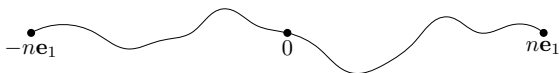
Theorem III: (A.-Hoffman) For every $\rho \in \mathcal{C}$, any two geodesics with Busemann function linear to ρ coalesce a.s.

Application I: The midpoint problem

Benjamini-Kalai-Schramm (2003): Does the geodesic between $(-n, 0)$ and $(n, 0)$ visit the midpoint?

Theorem: (A.-Hoffman) For diverging sequences $(u_n)_{n \geq 1}$ and $(v_n)_{n \geq 1}$

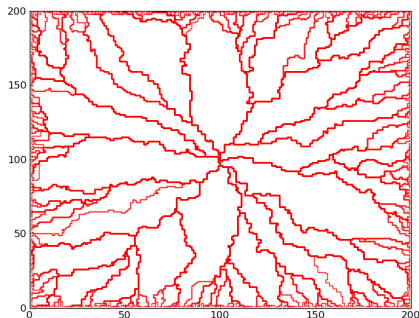
$$\mathbb{P}(0 \in \text{Geo}(u_n, v_n)) \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$



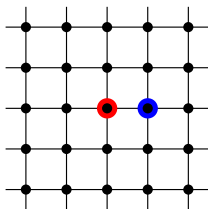
Application II: The highways and byways problem

Hammersley-Welsh (1965): What fraction of points at distance n from the origin lie on geodesics in \mathcal{T}_0 ?

Theorem: (A.-Hanson-Hoffman) The expected fraction tends to zero.



Application III: Existence and coexistence



In the **two-type Richardson model**, initially color $(0,0)$ **red** and $(1,0)$ **blue**. Uncoloured sites turn

red at rate $1 \cdot \#\{\text{red neighbors}\}$

blue at rate $\lambda \cdot \#\{\text{blue neighbors}\}$

Equivalent to FPP with exponential weights.

Corollary: (A.) For $\lambda = 1$ and $k \geq 1$ (including $k = \infty$) we have

$$\mathbb{P}(|\mathcal{T}_0| \geq k) > 0 \quad \Leftrightarrow \quad \exists x_1, x_2, \dots, x_k \text{ s.t. } \mathbb{P}(\text{Coex}(x_1, x_2, \dots, x_k)) > 0.$$

Application III: Proof

\Leftarrow : On the event $\text{Coex}(x_1, x_2, \dots, x_k)$, there are k disjoint infinite geodesics. Since disjoint they correspond to different functionals ρ . Since the set of functionals is constant, we have $|\mathcal{T}_0| = |\mathcal{C}| \geq k$.

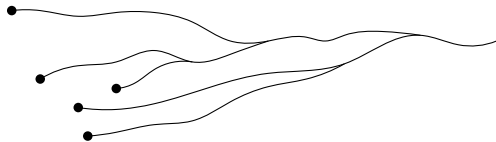
\Rightarrow : Suppose $|\mathcal{T}_0| \geq k$. Pick distinct functionals $\rho_1, \rho_2, \dots, \rho_k$ in \mathcal{C} . Position k points x_1, x_2, \dots, x_k at distance n from the origin in directions given by the gradients of $\rho_1, \rho_2, \dots, \rho_k$. Since Busemann functions are linear, for large n we have for every $i = 1, 2, \dots, k$

$$B_{\rho_i}(x_i, x_j) < 0 \text{ for all } j \neq i.$$

Hence, x_i is closer to far-out points on the geodesic corresponding to ρ_i .

Applications I-II: Proof

Corollary: (of Theorems I-III) Every shift-invariant measure on families of geodesics that **do not cross** is supported on families of geodesics containing at most four disjoint paths.

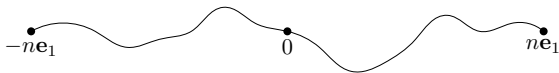


Solution to the midpoint problem

Theorem: (A.-Hoffman) For diverging sequences $(u_n)_{n \geq 1}$ and $(v_n)_{n \geq 1}$

$$\mathbb{P}(0 \in \text{Geo}(u_n, v_n)) \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Suppose: $\limsup_{n \rightarrow \infty} \mathbb{P}(0 \in \text{Geo}(-ne_1, ne_1)) > \delta$, derive contradiction.



Solution to the midpoint problem

- Consider vertical translates of this event.
- Construct a family of finite non-crossing geodesics.
- The construction induces a measure on non-crossing geodesics.
- Average and take a weak limit. The limiting measure is shift-invariant and supported on infinite non-coalescing geodesics.

