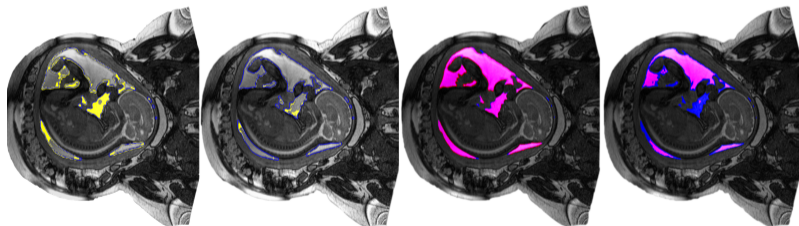


Split Conformal Prediction for Dependent Data

Paulo Orenstein

June 15th, 2022

IMPA



Joint work with Roberto Imbuzeiro Oliveira, Thiago Ramos, João Vitor Romano and others

Agenda

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- ▶ In practice: effect of dependency is negligible
- ▶ Conclusion: further directions

Video with blue solid.

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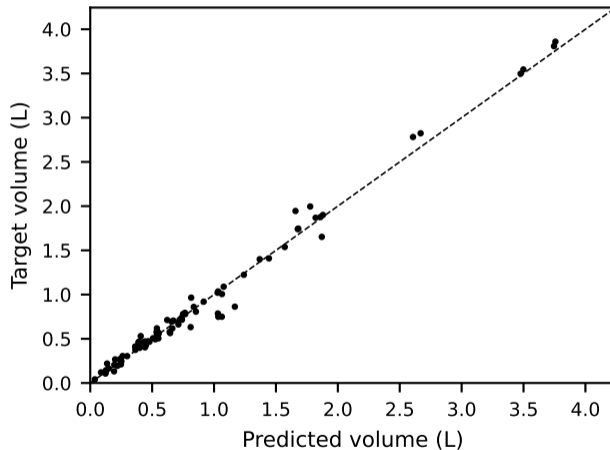
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- ▶ Goal: accurate algorithm for volume estimation, in seconds
- ▶ How: segment each layer in the MRI using U-Net, count voxel size for volume
- ▶ Results: $\sim 92\%$ Dice accuracy in under 5 seconds

Video with estimates.

Results



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 - "I'm 90% sure the true AF volume is between 2.72L and 2.88L"
 - "I'm 90% sure the true AF volume is between 1.90 and 3.70L"
- ▶ How can we provide valid predictive intervals for black-box prediction methods?

Given data $\{(X_i, y_i)\}_{i=1}^n$ to train any prediction method $\hat{\mu}$ and any level $\alpha \in (0, 1)$, can we construct a prediction set $C_{1-\alpha}(x)$ such that, for a new point (X_{n+1}, y_{n+1}) ,

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(For us, X_i is an MRI exam, y_i is the fluid volume, $\hat{\mu}$ is a U-Net, C is a rule specifying a volume interval for X_i .)

Conformal Prediction

- ▶ Conformal Prediction was proposed by Vladimir Vovk*

*Vovk, Gammerman, and Shafer. "Algorithmic learning in a random world", Springer (2005).

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[†]Angelopoulos and Bates, "A Gentle Introduction to Conformal Prediction", arXiv (2021).

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- ▶ We will consider the most popular incarnation: split CP[‡]

[‡]Lei, G'Sell, Rinaldo, Tibshirani, and Wasserman, "Distribution-free predictive inference for regression", JASA (2018).

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- ▶ Many recent variations and extensions, from regression to classification settings
- ▶ We will consider the most popular incarnation: split CP
- ▶ Important assumption: data $(X_i, y_i)_{i=1}^n$ is exchangeable (which is implied by iid)

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Proof sketch: since data is exchangeable, \hat{s}_j are also exchangeable. Consider the $1 - \alpha$ quantile of $\{\hat{s}_j\}_{j \in I_{\text{cal}}} \cup \{\hat{s}_k\}$; the probability of \hat{s}_k being bigger than the quantile must be bigger than $1 - \alpha$.

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So: $\mathbb{P}[\hat{s}_k \leq \hat{q}_{(1+1/n_{cal})(1-\alpha)}(\{\hat{s}_j\}_{j \in I_{cal}})] = \mathbb{P}[\hat{s}_k \leq \hat{q}_{(1-\alpha)}(\{\hat{s}_j\}_{j \in I_{cal}} \cup \{\infty\})] \geq 1 - \alpha.$ □

Split Conformal Prediction: Results

Empirical coverage

Conditional coverage

Split Conformal Prediction: Results

Empirical coverage

If the data $\{(X_i, y_i)\}_{i=1}^n$ is iid, then for any $\varepsilon > 0$ there exists $c_\varepsilon > 0$ such that

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If the data $\{(X_i, y_i)\}$ is iid and $\mathcal{A} \subset \mathcal{X}$ has finite VC dimension, then for any $A \in \mathcal{A}$ where $\mathbb{P}[X_k \in A]$ is not too small,

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Thus, split CP can guarantee coverage even if conditioned on some events.

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- ▶ Arbitrary discrepancy score $\hat{s}_{\text{tr}} : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$:
 - residuals: $\hat{s}_{\text{tr}}(x, y) = |y - \hat{\mu}(x)|$
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- ▶ Many more generalizations: e.g., prediction masks*

*Bates, Angelopoulos, Lei, Malik, and Jordan, "Distribution-free, risk-controlling prediction sets"

Results: Split CP

3D Slicer 4.11.20210226

File Edit View Help

Modules: Segment Editor

3DSlicer

Help & Acknowledgement

Segmentation: Segmentation

Master volume: exam

Add Remove Show 3D Segmentations...

Name
Segment_1

Effects

None Threshold Paint Draw Erase Level tracing Grow from seeds Fill between slices Margin Hollow Smoothing Scissors Islands Logical operators Mask volume Annotate

Annotate

Segment anisotropic fluid from a fetal MRI exam with machine learning. [Show details.](#)

Use CUDA acceleration

Volume Data (Last Run)

Best estimate: 666.63 mL

Confidence interval (90%): 603.68 mL to 777.58 mL

Run

Undo Redo

Masking

Data Probe

Show Zoomed Slice

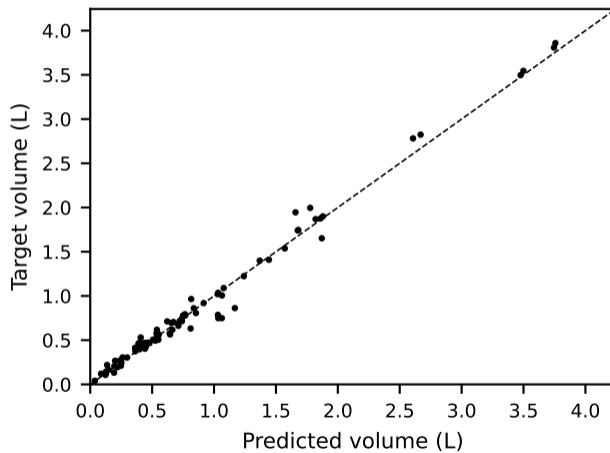
L
F
B

B: exam

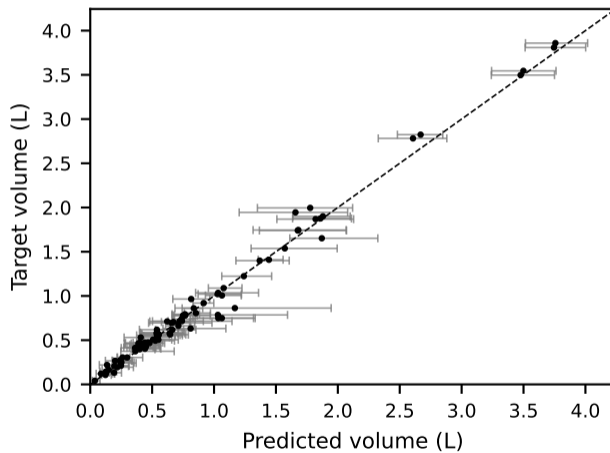
B: exam

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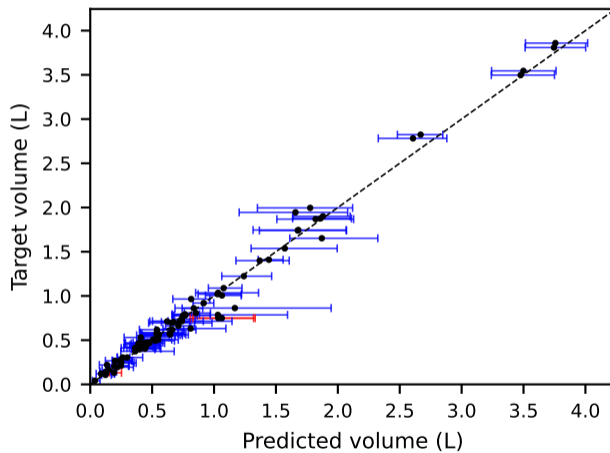
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(For us, some exams came from the same mother at different stages in the pregnancy.)

Dealing with Dependence

- ▶ Recent interest in independent data with distributional drift*

*Barber, Candès, Ramdas and Tibshirani. "Conformal prediction beyond exchangeability", arXiv (2022).

Dealing with Dependence

- ▶ Recent interest in independent data with distributional drift
- ▶ Our work[†]: rebuild split conformal prediction without exchangeability

[†]Oliveira, O., Ramos, Romano, "Split Conformal Prediction for Dependent Data", arXiv (2022).

Dealing with Dependence

- ▶ Recent interest in independent data with distributional drift
- ▶ Our work: rebuild split conformal prediction without exchangeability
- ▶ Intuition: see how data CDF concentrates when exchangeability is replaced by looser conditions:

$$\mathbb{P}[y_k \in C_{1-\alpha+\eta}(X_k)] \geq 1 - \alpha, \text{ so } \mathbb{P}[y_k \in C_{1-\alpha}(X_k)] \geq 1 - \alpha - \eta,$$

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- ▶ Tools: concentration inequalities and decoupling properties

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■ Stationarity: $(Z_t, \dots, Z_m) \stackrel{d}{=} (Z_{t+k}, \dots, Z_{t+m+k})$

■ β -mixing: $\beta(a) = \|\mathbb{P}_{-\infty:0,a:\infty} - \mathbb{P}_{-\infty:0} \otimes \mathbb{P}_{a:\infty}\|_{\text{TV}} \xrightarrow{a \rightarrow \infty} 0$

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► Data is time-invariant and asymptotically independent

Theoretical Results

▶ Assumptions on data:

■ Stationarity: $(Z_t, \dots, Z_m) \stackrel{d}{=} (Z_{t+k}, \dots, Z_{t+m+k})$

■ β -mixing: $\beta(a) = \|\mathbb{P}_{-\infty:0,a:\infty} - \mathbb{P}_{-\infty:0} \otimes \mathbb{P}_{a:\infty}\|_{\text{TV}} \xrightarrow{a \rightarrow \infty} 0$

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▶ Examples: Markov chains, renewal processes, AR(1)

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▶ Main theoretical tool: Blocking technique*

*Yu, "Rates of Convergence of Empirical Processes of Stationary Mixing Sequences", Annals of Probability (1994)

Main Theoretical Results

Marginal coverage

Empirical coverage

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Suppose that $\{(X_i, y_i)\}_{i=1}^n$ is stationary β -mixing. Given $\alpha \in (0, 1)$ and $\delta_{\text{cal}} > 0$, for $k \in I_{\text{test}}$,

$$\mathbb{P}[y_k \in C_{1-\alpha}(X_k)] \geq 1 - \alpha - \eta,$$

with $\eta = \varepsilon_{\text{cal}} + \varepsilon_{\text{tr}} + \delta_{\text{cal}}$, where $\varepsilon_{\text{tr}} = \beta(k - n_{\text{tr}})$.

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Empirical coverage

Suppose that $\{(X_i, y_i)\}_{i=1}^n$ is stationary β -mixing. Given $\alpha \in (0, 1)$ and $\delta_{\text{cal}} > 0$, $\delta_{\text{test}} > 0$:

$$\mathbb{P}\left[\frac{1}{n_{\text{test}}}\sum_{k \in I_{\text{test}}}\mathbb{I}_{[y_k \in C_{1-\alpha}(X_k)]} \geq 1 - \alpha - \eta\right] \geq 1 - \delta_{\text{cal}} - \delta_{\text{test}},$$

with $\eta = \varepsilon_{\text{cal}} + \varepsilon_{\text{test}}$.

The Details

$$\blacktriangleright F_{\text{cal}} = \{(a, m, r) \in \mathbb{N}_+^3 : 2ma = n_{\text{cal}} - r + 1, \delta_{\text{cal}} > 4(m-1)\beta(a) + \beta(r)\}$$

$$\blacktriangleright F_{\text{test}} = \{(a, m, s) \in \mathbb{N}_+^3 : 2ma = n_{\text{test}} - s, \delta_{\text{test}} > 4(m-1)\beta(a) + \beta(n_{\text{cal}})\}$$

$$\blacktriangleright \tilde{\sigma}(a) = \sqrt{1/4 + (2/a) \sum_{j=1}^{a-1} (a-j)\beta(j)}$$

$$\blacktriangleright \varepsilon_{\text{cal}} = \inf_{(a,m,r) \in F_{\text{cal}}} \left\{ \tilde{\sigma}(a) \sqrt{\frac{4}{n_{\text{cal}} - r + 1} \log \left(\frac{4}{\delta_{\text{cal}} - 4(m-1)\beta(a) - \beta(r)} \right)} + \frac{1}{3m} \log \left(\frac{4}{\delta_{\text{cal}} - 4(m-1)\beta(a) - \beta(r)} \right) + \frac{r-1}{n_{\text{cal}}} \right\}$$

$$\blacktriangleright \varepsilon_{\text{test}} = \inf_{(a,m,s) \in F_{\text{test}}} \left\{ \tilde{\sigma}(a) \sqrt{\frac{4}{n_{\text{test}}} \log \left(\frac{4}{\delta_{\text{test}} - 4(m-1)\beta(a) - \beta(n_{\text{cal}})} \right)} + \frac{1}{3m} \log \left(\frac{4}{\delta_{\text{test}} - 4(m-1)\beta(a) - \beta(n_{\text{cal}})} \right) + \frac{s}{n_{\text{test}}} \right\}$$

Conditional Theoretical Results

Marginal coverage, conditional version

Empirical coverage, conditional version

Conditional Theoretical Results

Marginal coverage, conditional version

Suppose that $\{(X_i, y_i)\}_{i=1}^n$ is stationary β -mixing. Given $\alpha \in (0, 1)$ and $\delta_{\text{cal}} > 0$, for any $k \in I_{\text{test}}$ and $K \in \mathcal{K}$ (with $\text{VC}(\mathcal{K}) = d$, $\mathbb{P}[X_k \in K] > \gamma$),

$$\mathbb{P}[y_k \in C_{1-\alpha}(X_k; K) \mid X_k \in K] \geq 1 - \alpha - \eta,$$

with $\eta = \varepsilon_{\text{cal}} + \varepsilon_{\text{test}}$.

Empirical coverage, conditional version

Conditional Theoretical Results

Marginal coverage, conditional version

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Empirical coverage, conditional version

Suppose that $\{(X_i, y_i)\}_{i=1}^n$ is stationary β -mixing. Given $\alpha \in (0, 1)$ and $\delta_{\text{cal}} > 0$, $\delta_{\text{test}} > 0$ and $K \in \mathcal{K}$:

$$\mathbb{P} \left[\inf_{K \in \mathcal{K}} \frac{1}{n_{\text{test}}(K)} \sum_{k \in I_{\text{test}}(K)} \mathbb{I}_{[y_k \in C_{1-\alpha}(X_k; K)]} \geq 1 - \alpha - \eta \right] \geq 1 - \delta_{\text{cal}} - \delta_{\text{test}},$$

with $\eta = \varepsilon_{\text{cal}} + \varepsilon_{\text{test}}$.

The Details

$$\blacktriangleright G_{\text{cal}} = \{(a, m, r) \in \mathbb{N}_+^3 : 2ma = n_{\text{cal}} - r + 1, \delta_{\text{cal}} > 16(m-1)\beta(a) + \beta(r)\}$$

$$\blacktriangleright G_{\text{test}} = \{(a, m, s) \in \mathbb{N}_+^3 : 2ma = n_{\text{test}} - s, \delta_{\text{test}} > 8(m-1)\beta(a) + \beta(n_{\text{cal}})\}$$

$$\blacktriangleright \varepsilon_{\text{cal}} = \inf_{(a,m,r) \in G_{\text{cal}}} \left\{ \frac{1}{\gamma} \left(4\sqrt{\frac{\log(2(m+1)^d)}{m}} + \frac{2(r-1)}{n_{\text{cal}}} + 2\sqrt{\frac{1}{2m} \log\left(\frac{16}{\delta_{\text{cal}} - 16(m-1)\beta(a) - \beta(r)}\right)} \right) \right\}$$

$$\blacktriangleright \varepsilon_{\text{test}} = \inf_{(a,m,s) \in G_{\text{test}}} \left\{ \frac{1}{\gamma} \left(4\sqrt{\frac{\log(2(m+1)^d)}{m}} + \frac{2s}{n_{\text{test}}} + 2\sqrt{\frac{1}{2m} \log\left(\frac{8}{\delta_{\text{test}} - 8(m-1)\beta(a) - \beta(n_{\text{cal}})}\right)} \right) \right\}$$

Application: Autoregressive Process

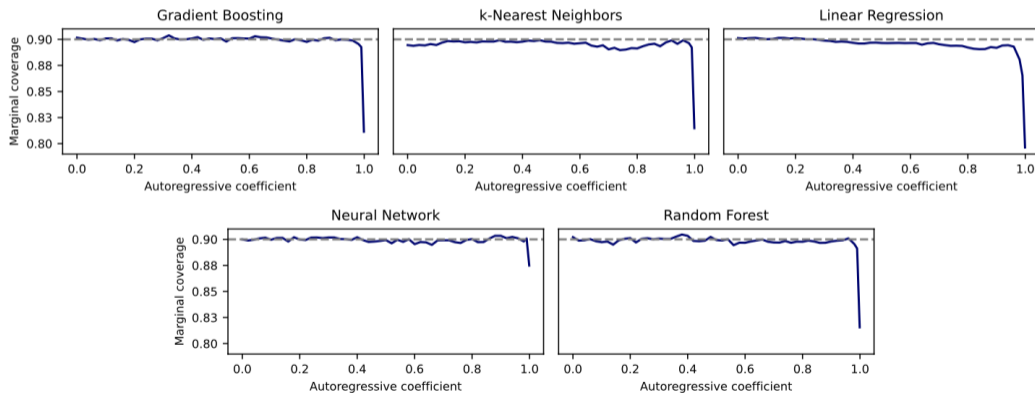
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Application: Finance

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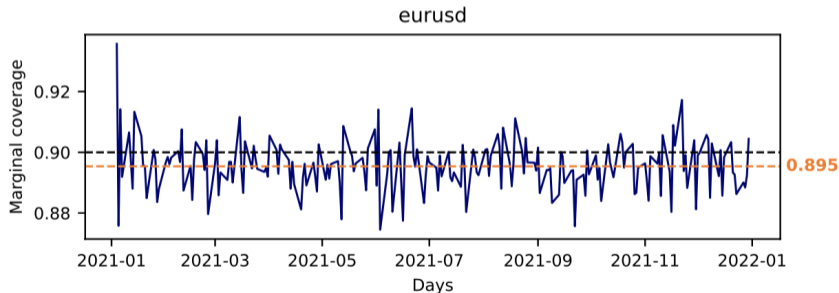
- ▶ Time series with EUR/USD spot exchange rate; predictions with boosting
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Application: Empirical Coverage

- ▶ Two-state hidden Markov model

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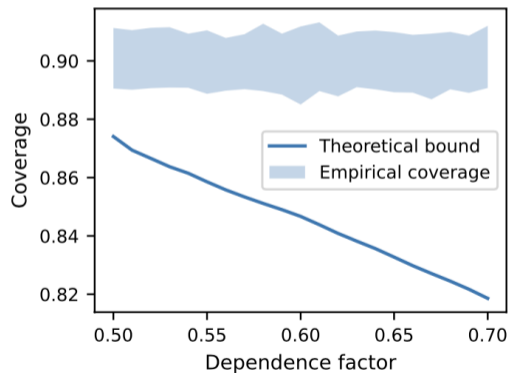
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- ▶ Our results can be extended beyond stationarity and to non-split CP (e.g., rank-one-out, risk-controlling prediction sets).
- ▶ There is much more theory and algorithms to be developed on top of it.

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